

Skin Cancer Detection in Deep Learning Using Restnet-50 Model

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Abstract- Pore and skin cancers are one of the riskiest types of cancer. DNA is a type of nucleic acid. Breaks in skin cells that do not get fixed cause genetic flaws or mutations in the skin, which is how skin malignancies develop. Pores and skin cancers have the inclination to step by step spread over different bits components, so it is curable in initial ranges, which is why it's far more pleasant to detect at early ranges. Due to the increased prevalence of skin cancer, its high mortality rate, and the high price of medical treatments, it is crucial to understand the early warning signs of skin cancer. Due to the importance of these issues, researchers have created a variety of primary detection techniques for skin and pore cancers. The characteristics of a lesion include its symmetry, colouring, duration, form, and so on. Are used to discover most cancers and differentiate benign pores and skin cancers from most cancers. This paper gives an in-depth systematic overview of deep learning techniques for detecting pores and skin cancer early. Study papers posted in popular and well-reputed periodicals, appropriate to the problem of pores and pores and skin most cancers diagnosis had been analysed. Study results are provided in equipment, charts, graphs, strategies, as well as models for higher data.

Keywords: Acrylic keratosis, basal cell cancer, CNN, Melanoma, Benign Keratosis-like lesions, Skin cancer lesions in the veins, Segmentation, dermatofibroma.

I. INTRODUCTION

An extremely hazardous condition, skin cancer. There are around 5.4 million original cases of skin cancer individually year, according to my study BuljanM [1] Cipto H [2] Md Ashrafal [4]. Additionally alarming Winsya H [3] Serban Radu SJ [5] are the global statistics. New melanoma cases were discovered annually at a rate of 53% more from 2008 to 2018 according to current studies. Within following ten years, it is anticipated that this disorder will become more fatal. Identifying in later ranges results in a survival charge of less than 14% Khalid M [8], Marwan AA [9], Mousumi Roy

[10,12]. However, the survival rate is close to 97% Winsya H [3] if skin cancer is found at an early stage. This calls for early detection of pore and skin cancer. This study provides a highly accurate solution to the early analysis problem.

A professional dermatologist is known to frequently do a number of treatments, start through a stark-naked eye statement of suspicious lesions, followed by dermatologic imaging (mapping lesions microscopically), and concluding with observation by biopsy. The affected person might also progress to subsequent phases, and this would eat up time. Additionally, a clinician's competence level determines whether an analysis is valid; it is subjective. The accurate

diagnosis of skin malignancies by a skilled dermatologist has been reported to be less than 80% Nazia Hameed [6]. Including those problems, there aren't many skilled dermatologists to be had globally in public healthcare. There has been significant research of remedies by means of developing computer image evaluation algorithms, which will identify skin malignancies quickly and to the early stage and overcome some of the challenges listed above Bisla D. [14,25]. These algorithmic responses' audiences were parametric, which implies that records had to be widely disseminated in order for them to be understood. Since information's nature cannot be regulated, those techniques might not be sufficient to appropriately identify the condition. The need that the statistics be in normal distribution form is no longer a requirement for non-parametric responses.

The use of in-depth learning has been made possible in this paper through augmented dermatologist aid. The basic idea behind the method is that a computer can identify the issue by looking at skin cancer photographs. Because the laptop version can be evolved without any programming knowledge, the presentation is innovative. It has been found that this model's quality is 100% and its average diagnosis accuracy is roughly 98.89%. The difficulty of being put off, accuracy, and the dearth of dermatologists in public health are all overcome by the machine-assisted analysis presented here.

II. LITERATURE SURVEY

The research on contemporary pores and identifying skin cancer primarily depending on picture Analyses have superior extensively finished time. Several unique strategies have been attempted BuljanM, [1]. The latest worldwide skin imaging collaboration (ISIC) event in 2018 established itself as a de facto benchmark for skin cancer diagnostics by holding a project competition. Another claim makes it possible to discover skin and pore cancer using a mobile app. In a majority of those researchers' attempts have been made to enhance the with regard to present-day evaluation with the aid of using particular category algorithms and strategies. The field of photography reached new heights after Fukushima (1988) and later Le-Cunn (1990) introduced the convolutional neural network (CNN) structure. For photograph type, they used CNNs. CNNs are thought to be adequate algorithms for picture classification since they essentially replicate the human seen cognition system. Even though there's a plethora of contemporary literature to be had on photograph type, we restrict our assessment of present-day literature to deep today's techniques for skin most cancers images. Step one forward on pores and pores and skin most cancers type through a pre-educated Google Net Inception V3 CNN version got here from Esteva et al. Ashraf R[19] They used 3,374 dermatoscopic photos from the 129,450 medical photographs of skin malignancies with the highest incidence. The alleged accuracy of the trendy kind is 72.11 0.9. In 2016, Yu et al. Khan M.Q [20] advanced a CNN with more than 50 layers on the ISBI 2016 task dataset for the category of contemporary malignant most tumors maximal malignancies. According to this project, the kind accuracy was changed to 85.5%. Haenssle et al. Rashid H. [13,21] classified binary diagnostic dermatoscopy melanocytic pictures using a deep convolutional neural network in 2018, and they suggested an

86.6% sensitivity and specificity for type. According to Dorj et al.'s research in Ref. Byrd A.L. Elgamel M [23], deep cutting-edge CNN combined with ECOC SVM performed better in a multiclass class. The strategy was to classify multiclass records using ECOC SVM in conjunction with pre-trained Alex Net Deep extremely-current CNN. This paper reports a modern 95.1% median accuracy. Han et al. classified the clinical images of 12 modern skin conditions in Ref. Elgamel M [23] using a deep convolutional neural network. The stated fine classification accuracy instance fluctuates between 96.0% and 1%. The scope of this paper's ultramodern analysis does not usually include a thorough review of contemporary classifiers, although Bisla D [24] provides a methodical analysis of contemporary deep classifiers. A. Vijayaraj et al. [24] state that a gateway's purpose is to both increase throughput and decrease congestion; it is also used as a means of providing a congestion notification system. The proposed system by A. Vijayaraj et al. [25] makes use of zone routing protocol (ZRP). In the "Pro-active" protocol, if the sender and the recipient are in the same location, the packet is sent to the recipient right away. The method put forth by Bhuyan et al. [28] makes use of a deep neural network framework to create hidden information from multiple images that are combined into a single one. Based on the massive image transfer, sophisticated deep learning techniques are applied to identify common image alterations. In order to address cloud security, Anand et al. [29] present a novel cybersecurity architecture that combines chaotic chemotaxis and genetic crossover operation algorithm (GBFO) with genetic crossover architecture. employing an ideal key generation method based on the ratio of hiding, alteration, and preservation of data.

Deep learning has revolutionized the entire landscape brand new device trendy sooner or later contemporary a long term. it's by far considered the maximum system state-of-the-art subfield involved with artificial neural community processes. those Using algorithms stimulated through the usage of the Structure and operation cutting-edge the individual mind. A wide range of fields, including speech reputation Xinyuan Zhang [7,15], sample reputation Khalid M [8], and bioinformatics Marwan AA [9,17], implement deep learning current learning methodologies. Deep contemporary systems have produced astounding results in these packages when compared to extraordinary classical procedures and contemporary systems today in recent years, a number of sophisticated contemporary procedures were applied to detect skin cancer using computers. Based on recent, in-depth research, in this paper, we comprehensively examine and discuss strategies for detecting skin tumors. Modern deep learning methods for detecting skin and pore cancer, such as Artificial Neural Networks (ANN), Convolutional Neural Networks (CNN), Korhonen Self-Organizing Neural Networks (KNN), and Generative Adversarial Networks (GAN), are the focus of this paper. Recent years have seen a lot of research on this subject. The results of the investigations that are already available must therefore be compiled, examined, categorized, and summarized. In order to carry out an important systematic evaluation of modern skin cancer detection techniques using

deep neural community-based kinds, we developed search strings to acquire relevant data. We limited our search to conferences and courses from recent, reputable periodicals. 51 pertinent studies papers had been chosen based on the multi-degree preference standards and assessment process we had installed. The papers have undergone thorough evaluation and analysis based on specific factors.

III. EXISTING SYSTEM

In order to determine if a patient has skin cancer or not, he needs to undergo individual screening with the aid of a dermatologist. Dermatologists can treat a variety of cases much more swiftly than they might have anticipated with the use of this framework. Several symptomatic checklists were connected. It is on the list R. Delila Tsaniyah [11], which also contains: Asymmetry(A): The problem is that the tumor-containing portion of the detected mobile does not coordinate with the other half of the Wattage, which in this case is 1.3. The border(B)-the rims/the edge of the polluted cells wind up damaged, scored, and veiled. The wattage for this related issue is 0.1. There are variations in color(C)-color. Sunglasses with tan or dark-colored patches on the skin are available.

A. METHODOLOGY

A smart class algorithm and an automatic skin lesion segmentation were created by the authors of this work entirely from thermoscopic images. In this case, we performed gadget learning using a CNN and Resnet-50.

Blue, white, and purple splotches add to the disgusting image. This aspect uses 0.5 watts of power. Diameter (D)-The cell width finally proves to be more significant than 6mm and above. Malignant Melanoma is indicated by Evolution(E) previously stated alterations or upgrades.

IV. PROPOSED SYSTEM

Convolution neural networks are an essential kind of deep neural networks that are properly used in computer vision. Its miles are used for image categorization, compiling an input image set, and performing image reputation. By developing more honest skills, such curves and edges, CNN is a fantastic tool for learning and compiling local and international data in addition to forms and corners Farag A [16,26]. A few of the hidden layers CNN uses are convolution, nonlinear pooling, and completely linked layers Schlosser R.W [26]. A number of obviously connected layers may combine to form some of the convolution layers that make up CNN. The three main kinds of layers utilized in CNN are convolution, pooling, and totally connected layers.

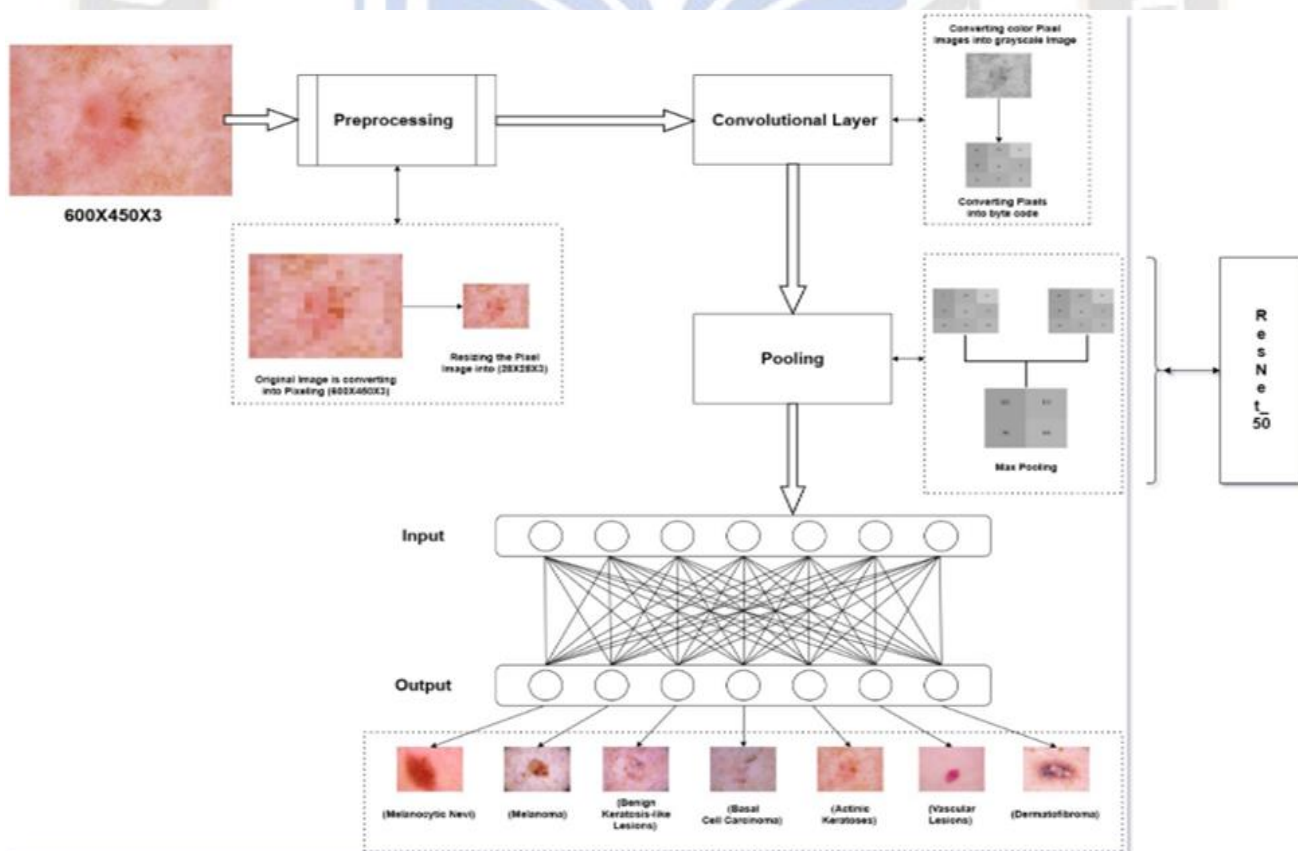


Figure 1 System Architecture

B. DATASET OVERVIEW

Skin cancers and pores the reference datasets for this inquiry are from MNIST: HAM10000 [19]. A useful source of information for the prognosis of skin cancer is the CC-through-NC-SA-40 approved dataset. To assemble the statistics, Kaggle's open Imaging Archive has been used. For educational purposes, a dataset consisting of an average of ten half-JPEG skin cancer teaching images from two different locations—one in Queensland, Australia, and the other in Vienna, Austria—has been assembled. To save screenshots

and metadata, the Australian website used PowerPoint files and Excel databases. The Austrian website started collecting images using analogue cameras and stored them in various forms. A ramification of methodologies is advised primarily based on the research. Pores and skin cancer detection on this test is trained using data from this benchmark, the Resnet-50, and the advised CNN. Each benign keratosis-like lesion was included in this dataset, which covers all of the essential diagnostic subcategories for pigmented lesions.

TABLE 1. Dataset values for various pixels from head.

	Pixel10000	Pixel10001	Pixel10002	Pixel10003	Pixel10004	...	Pixel2350	Pixel2351	Label
0	192	153	193	195	155	...	154	177	2
1	25	14	30	68	48	...	14	27	2
2	192	138	153	200	145	...	104	117	2
3	38	19	30	95	59	...	12	15	2
4	158	113	139	194	144	...	78	92	2

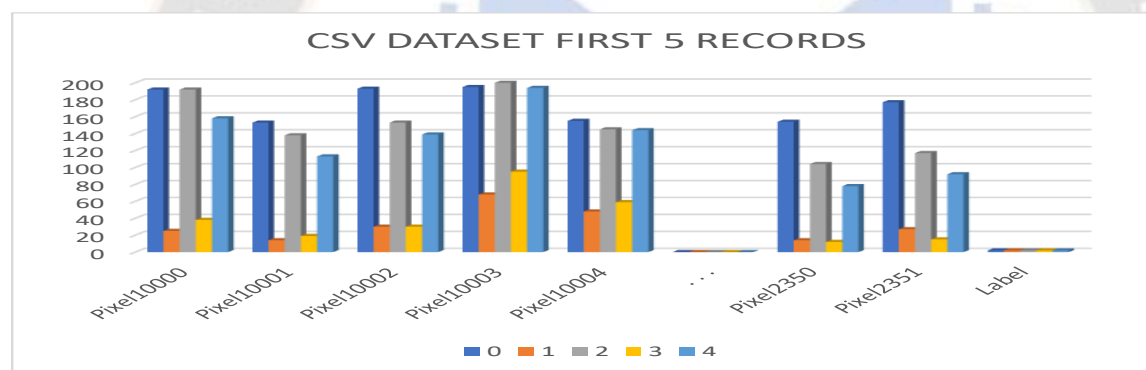


Figure 2. MNIST: HAM10000

C. HAM10000

A dataset called HAM10000 that measures how closely humans are to gadgets and has 10,000 training snapshots may exist. It solves the problem of a lack of variance and is by far the latest dataset on skin lesions that is publicly available Cliff Rosendahl's skin cancer study in Queensland, Australia, and the dermatology department of the medical university of Vienna, Austria, both donated 10.5 thermoscopic images to the HAM10000 collection. Over a 20-year span, this series

was created. Dermatological doctors at the medical college of Vienna, Austria, received and kept detailed copies of lesions before virtual cameras became commonly utilized. These photographic prints were converted into eight-bit, 300 DPI-fine JPEG images using a Nikon-Coolscan-5000-ED scanner produced by the Nikon agency Japan. After carefully cropping each image, the resolution was changed to 800 by 600 and the DPI increased to 72.

TABLE 2. Dataset values for various pixels from tail.

	Pixel10000	Pixel10001	Pixel10002	Pixel10003	Pixel10004	...	Pixel2350	Pixel2351	Label
10010	183	165	181	182	165	...	187	189	0
10011	2	3	1	38	33	...	4	1	0
10012	132	118	118	167	149	...	151	145	0
10013	160	124	146	164	131	...	162	172	0
10014	175	142	121	181	150	...	139	126	0

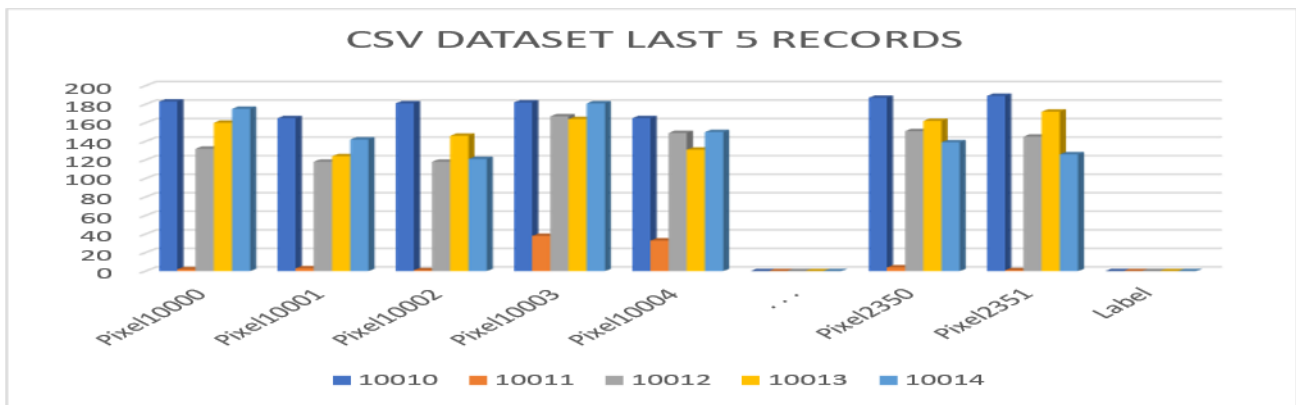


Figure 3. HAM10000

V. PROPOSED METHODOLOGY

The suggested method's overall approach, which is entirely dependent on the dataset provided in this text, has been utilized to create a larger automated model of skin lesion types. The proposed version's full operational approach demonstrates the practical structure of that module. Thermoscopic skin lesion photos are implemented to helpful resources within the class of skin and pores and skin malignancies. After preprocessing, kind and Resnet-50/CNN-based total training are the primary steps in the given model's functioning. ESRGAN is used to perform the preliminary preprocessing step, which includes image first-rate development. Ground fact pix are then used to decide an augmented photo's region of interest (ROI) for every segmented lesion. Eventually, the Dermatoscopy picture is sent to the Resnet-50/CNN fashions for on-the-spot pores and skin lesions and clever classification schooling and publicity. A smart class version and an automated manner for segmenting pores and skin lesions are used to create the subsequent sections of the studies test, which might be defined as sizeable on every degree in the technique.

Convolutional Neural Network

CNNs are the chosen network architecture for recognising and detecting objects, despite the fact that there are numerous distinct types of neural networks in deep learning. CNNs are a particular kind of network architecture that are employed in the processing of pixel input as well as in activities like image recognition. A common deep neural network for image and video identification applications is the CNN, or Convolutional Neural Network. The mathematical equation for a basic convolutional layer in a CNN can be represented as follows:

$$Y_{i,j,k} = \sum_{m=1}^M \sum_{n=1}^N \sum_{l=1}^L X_{i+m-1,j+n-1,l} \times W_{m,n,l,k} + B_k \quad (1)$$

where X the source image or map of features, W is the set of learnable convolutional filters, B is the bias term, and Y is the output

feature map. The indices i, j, k represent the spatial location and channel of the produced feature map pixel, while m, n, l represent the spatial location and channel of a pixel in the input feature map and filter, respectively. The summation over m and n both the activation function and the convolution operation are represented. can be Used in the result Y to introduce non-linearity and improve model performance. The summation over m and n represents the convolution operation, and the activation function is applied to the output to introduce non-linearity and improve model performance. The pooling layer can be represented mathematically as:

$$Y_{i,j,k} = \text{pool}(X_{i+K-1:j+K-1,k}) \quad (2)$$

the output feature map is Y , and X is the input feature map. $\text{pool}(\cdot)$ remains a pooling function such as average or maximum pooling, and K is the size of the pooling window. Mathematically speaking, the fully connected layer is represented by

$$Y = f(WX+B) \quad (3)$$

wherever X is the input vector, W is the set of learnable weights, B is the bias term, Y is the output vector, and $f(\cdot)$ is an activation function, such as the sigmoid or SoftMax function. Overall, a CNN combines these layers in a hierarchical manner from the source image's feaures or video and make predictions based on those features.

A CONVOLUTIONAL LAYER

The middle layer of the convolutional mind organization, the convolutional layer, has many detail maps. Each detail map is made up of several neurons, each of which is internally formed with a pixel at every place and is privately connected to the beyond layer's problem manual using a convolution element. Ashraf R [19] The convolutional layer separates enter highlights via a convolution interest, the primary layer gets rid of low-stage highlights like edges and contours, and additional big-stage convolutional layers separate more elevated degree Rashid H [21]. The element map in the data layer is locally connected to the neurons in the first

convolutional layer, and the privately weighted mixture is communicated with higher multiplied degree highlights. The neurons in the first convolutional layer are privately associated to the problem map within the statistics layer, then the privately biased combination is communicated to the nonlinear actuation capability, through which the final value is 0 Byrd A.L [22].

POOLING LAYER

The pooling layer is connected to the convolution layer and is made up of several highlight maps. Without changing the quantity of element maps, each element map is externally compared to the detailed guide of the beyond layer. The local connections between the neurons in the convolution layer's records layer of the pooling layer and those in the convolution layer allow the convolution layer to satisfy J. Duchi [18] Byrd A.L., [22]. The purpose of the comprehensive manual is to obtain highlights with spatial invariance, which the pooling layer attempts to reduce. Maximum severe pooling and imply pooling are the most often used pooling strategies. The most extreme pooling is to use the good mark. When all other factors are equal, the advised pooling is to take the average well worth in the nearby area. The pooling layer is the window through which the beyond layer is slid into view Bisla D [24].

Fully connected layer

After building a few convolutional layers and pooling layers, CNN associates one or instead additional totally linked layers. Individually neuron within a reality-related layer is truly related to all neurons within the past layer Schlosser R.W. [26]. The enactment functionality of every neuron inside the absolutely associated layer through huge purposes the ReLU functionality. The last truly related layer's final result value is delivered to the result layer, where the SoftMax functionality can be used for grouping. Dropout innovation is frequently used within the entirely associated layer in order to prevent making gear-up overfitting Farag A., [25]. Through this innovation, a few hotspots for the mystery layer quickly emerge. These hubs do not participate in CNN's generative mechanism, which reduces the complexity of shared versions and gives neurons the ability to devise new strategies for accumulating more robust highlights Schlosser R.W. [26].

The Convolutional Neural Network (CNN) algorithm uses a number of mathematical operations to separate out features from the input data and categories them. A CNN can be expressed in general terms as follows:

Convolutional Layer

$$\text{Output} = \text{Activation} (\text{Convolution} (\text{Input}, \text{Weights}) + \text{Bias}) \dots\dots (4)$$

Pooling Layer

$$\text{Output} = \text{Pooling} (\text{Input}) \dots\dots\dots (5)$$

Fully Connected Layer:

$$\text{Output} = \text{Activation} (\text{Input Weights} + \text{Bias}) \dots (6)$$

In the formula above, Input stands for the input data, Weights for the CNN's learnable parameters, and Bias for the bias term that is applied to the convolutional or fully connected layer's output. The Convolutional Layer uses a series of learnable filters (Weights) towards perform a convolution operation on the input data in instruction to excerpt features from the input image. To add nonlinearity, an activation function is added to the layer's output. The pooling layer lowers the feature map's dimensionality by down sampling it. By doing this, overfitting is avoided and the computational complexity of the system is decreased. The Fully Connected Layer increases the input via the weights in a matrix then before adds the bias term to produce the final output. An activation function is additionally applied to the layer's output to introduce nonlinearity. The CNN's parameters are learned during training using backpropagation and gradient descent, and predictions are made using the output of the final layer. Mathematical terms The mathematical formula for a Convolutional Neural Network (CNN) involves several mathematical operations, including convolution, pooling, and fully connected layers. Here is the general mathematical formula for a CNN: Convolutional Layer Output = Activation (Convolution (Input, W) + b) Where Input denotes the input data, W denotes the filter weights, b denotes the bias term, Convolution denotes the convolution operation, and Activation denotes the activation function applied to the convolution operation's output. **Pooling Layer:** Output = Pooling (Input) In this case, supplied refers to the data being supplied, while Pooling denotes the pooling process being used on the data.

Fully Connected Layer:

$$\text{Output} = \text{Activation} (\text{Input} \times \text{W} + \text{b}) \dots\dots\dots (7)$$

Input refers to the input data, W refers to the weight matrix, b refers to the bias term, Input x W refers to the matrix multiplication operation, and Activation refers to the activation function applied to the matrix multiplication operation's output. Because of its superior performance in computer vision tasks, particularly image recognition, ResNet-50, a deep neural network design, has gained popularity. Researchers from Microsoft Research Asia initially presented it in 2015, and both businesses and academics have since largely embraced it.

The number of layers in the network, which is substantially deeper than earlier neural network topologies, is indicated by the "50" in ResNet-50. The network is built on a residual learning architecture, enabling deeper neural networks to be trained more effectively. By establishing shortcut connections that skip one or more layers, it is possible to achieve this and enable information to move directly from the input to the output.

ResNet-50 is made up of various constituent parts known as residual blocks. Each residual block has a shortcut connection that skips the layers and comprises of two or more convolutional layers. A non-linear activation function (in this case, a Before combining the output of the convolutional layer with the output of the shortcut connection, the Rectified

Linear Unit (ReLU) is utilized. running the convolutional layer.

Following is a breakdown of the architecture's layers and the number of parameters in each layer:

Image input layer: $224 \times 224 \times 3$

Convolutional layer: stride of 2, padding of 3, 7×7 kernel size, 64 filters. Number of variables: $(7 \times 7 \times 3 \times 64) + 64 = 9,472$

Layer for batch normalization 128 parameters

Maximum pooling layer: kernel size of 3×3 , the stride of 2. 0 parameters
 64 filters make up residual block 1. $1 \times 1 \times 64 \times 64$, $3 \times 3 \times 64 \times 64$, and $1 \times 1 \times 64 \times 256$ together equal 16,896. 128 filters make up the residual block 2. $(1 \times 1 \times 128 \times 128)$ plus $(3 \times 3 \times$

$128 \times 128)$ plus $(1 \times 1 \times 128 \times 512)$ equal 73,856. 256 filters in residual block 3. The following parameters add up to 295,168: $(1 \times 1 \times 256 \times 256) + (3 \times 3 \times 256 \times 256) + (1 \times 1 \times 256 \times 1024)$ 512 filters are in residual block 4. $1 \times 1 \times 512 \times 512$, $3 \times 3 \times 512 \times 512$, and $1 \times 1 \times 512 \times 2048$ are the parameters. The average pooling layer has a 7×7 kernel size. 0 parameters: 1000 classes in a fully connected layer. Number of variables: $(1 \times 1 \times 2048 \times 1000) + 1000 = 2,049,000$. About 25.6 million parameters make up the entire ResNet-50 dataset. ResNet-50 has proven to perform at the cutting edge in a number of image recognition tasks, including object identification, image classification, and picture segmentation. Due to its success, deeper and more intricate neural network architectures like ResNet-101 and ResNet-152, which have even more layers and parameters, have been developed.

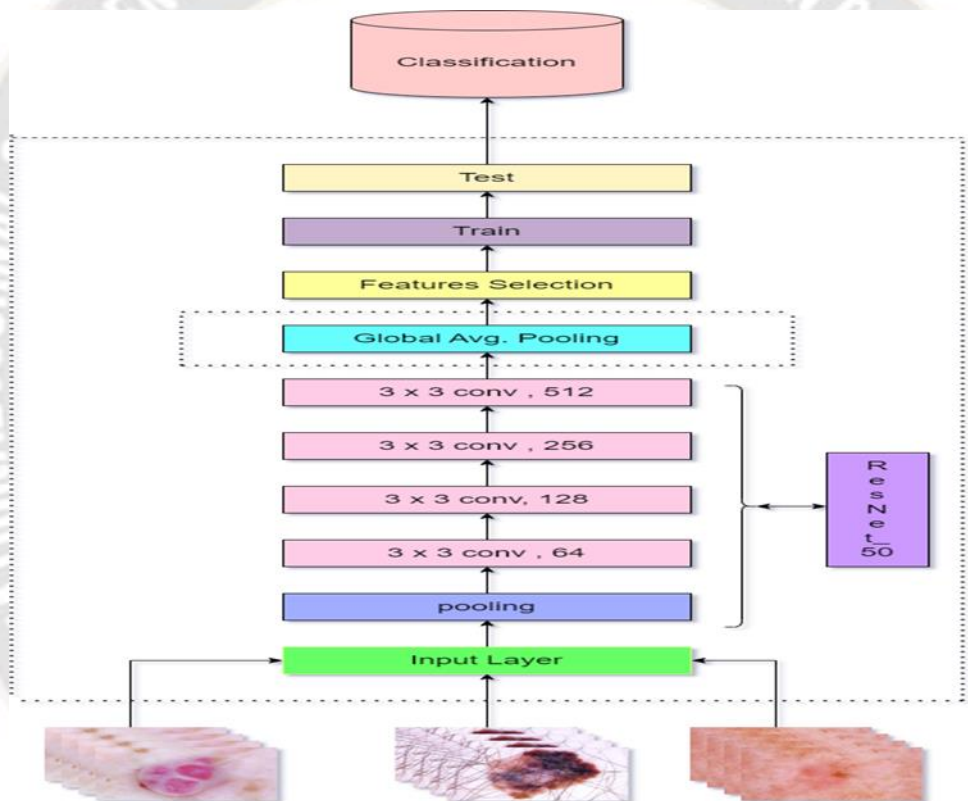


Figure 4. ResNet_50 Architecture

Convolutional operation: To extract features from input images, ResNet-50's convolutional layers employ the convolutional mathematical operation. The 2D convolution formula is:

$$(f * g)(i, j) = \sum_m \sum_n f(m, n) * g(i-m, j-n) \quad (8)$$

where * denotes the convolution procedure, g is the kernel (sometimes referred to as the filter), and f is the input picture. The element-wise product of the kernel and the appropriate region of the input picture is added to produce the output at location (i, j).

Image input layer: $224 \times 224 \times 3$

Convolutional layer: stride of 2, padding of 3, 7×7 kernel size, 64 filters. Number of variables: $(7 \times 7 \times 3 \times 64) + 64 = 9,472$

Layer for batch normalization 128 parameters

Maximum pooling layer: kernel size of 3×3 , the stride of 2. 0 parameters

64 filters make up residual block 1. $1 \times 1 \times 64 \times 64$, $3 \times 3 \times 64 \times 64$, and $1 \times 1 \times 64 \times 256$ together equal 16,896. 128 filters make up the residual block 2. $(1 \times 1 \times 128 \times 128)$ plus $(3 \times 3 \times 128 \times 128)$ plus $(1 \times 1 \times 128 \times 512)$ equal 73,856. 256 filters in residual block 3. The following parameters add up to 295,168: $(1 \times 1 \times 256 \times 256) + (3 \times 3 \times 256 \times 256) + (1 \times 1 \times 256 \times 1024)$ 512 filters are in residual block 4. $1 \times 1 \times 512 \times 512$, $3 \times 3 \times 512 \times 512$, and $1 \times 1 \times 512 \times 2048$ are the parameters. The average pooling layer has a 7×7 kernel size. 0 parameters: 1000 classes in a fully connected layer. Number of variables: $(1 \times 1 \times 2048 \times 1000) + 1000 = 2,049,000$. About

25.6 million parameters make up the entire ResNet-50 dataset. ResNet-50 has proven to perform at the cutting edge in a number of image recognition tasks, including object identification, image classification and picture segmentation. Due to its success, deeper and more intricate neural network architectures like ResNet-101 and ResNet-152, which have even more layers and parameters, have been developed. Residual block: ResNet-50 contains residual blocks that use a shortcut connection to skip one or additional layers. Before passing through a Activation function that is nonlinear (ReLU), this shortcut connection is introduced to the convolutional layers' output. A residual block has the following formula:

$$F(x, "W_i") + x = y \dots\dots\dots(9)$$

When W_i are the learnable parameters for the convolutional layers and the input is x . to the block, The result is y , F is the residual function (composed of convolutional layers and ReLU activation), and y is the output.

COMPARISON

Early diagnosis is essential in the treatment of skin cancer Nazia Hameed [6]. For the most part, clinicians diagnose skin cancer using the biopsy procedure. In order to do a scientific examination to identify whether or not a suspected skin lesion is malignant, this procedure extracts a pattern from the lesion. This method is uncomfortable, cumbersome, and slow. Skin cancer symptoms can now be quickly, affordably, and comfortably diagnosed thanks to computer-based technology. It is advised to check the symptoms and determine whether melanoma or other skin malignancies are to blame for them using a number of non-invasive approaches. not. Obtaining the image, preprocessing it, segmenting the resulting pre-processed image, extracting the desired feature, and classifying it are the general steps in the detection of skin and pore cancer.

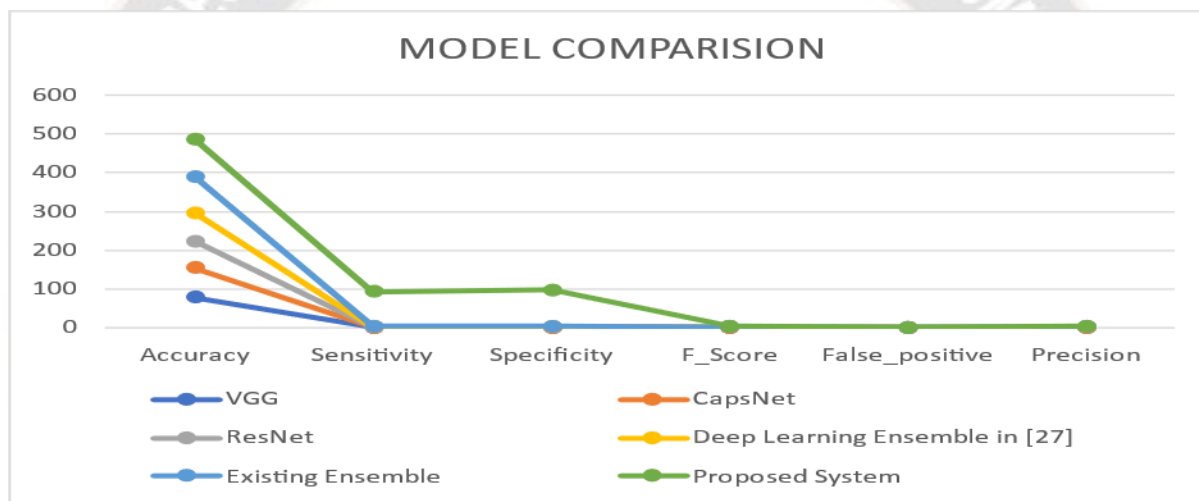


Figure 5. Model Comparison

TABLE 3. Performance evaluation between the individual learners and the provided ResNet-50 approach.

Models	Accuracy%	Sensitivity%	Specificity%	Score%	False_positive%	Precision%
VGG16	79.0	0.67	0.92	0.79	0.08	0.92
Caps Net	75.05	0.73	0.78	0.75	0.24	0.78
Res_Net	69.04	0.76	0.65	0.69	0.38	0.68
Deep Learning Ensemble in [26]	73.04	0.83	0.64	0.68	0.46	0.68
Existing Ensemble	93.05	0.89	0.88	0.95	0.08	0.96
Proposed System	96.94	89.0	94.01	0.94	0.05	0.9

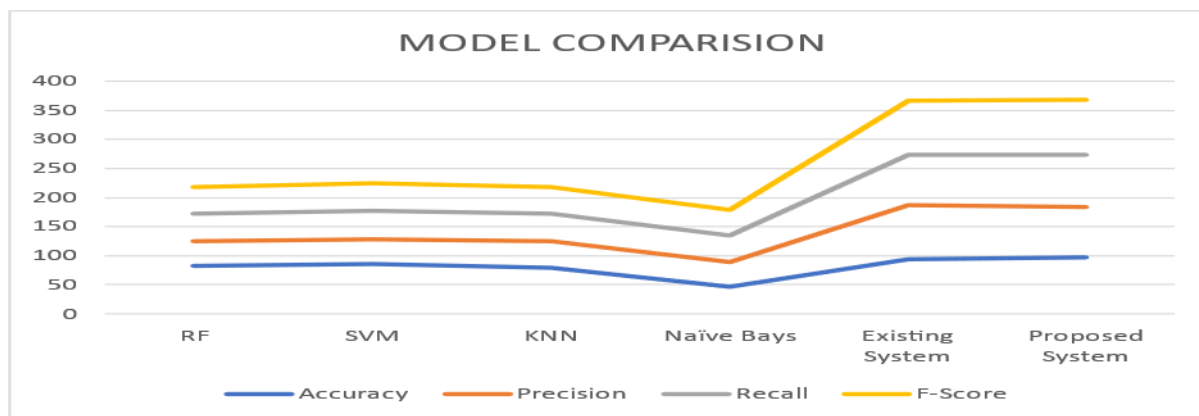


Figure 6. Comparison Graph

A. EXPERIMENTAL RESULTS

TABLE 4: Performance comparison between the suggested technique and several machine learning representations

Model	Accuracy%	Precision%	Recall%	F-Score%
RF	81.25	45.36	49.12	42.56
SVM	84.2	43.6	52.45	43.86
KNN	76.27	44.45	45.66	44.56
Naïve Bays	48.63	45.52	46.56	42.52
Existing System	94.55	95.09	85.08	93.23
Proposed System	96.94	87.02	90	94

The HAM10000 dataset, a benchmark open database for gadget mastery, was used to train and test the pre-professional models (MODEL2-MODEL5) mentioned above. The facts were broken down into 80:10:10: Training: Validation: Trying out ratios.

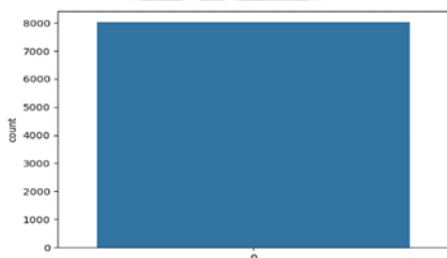


Figure 7. exploratory data analysis and preprocessing to get unique images.

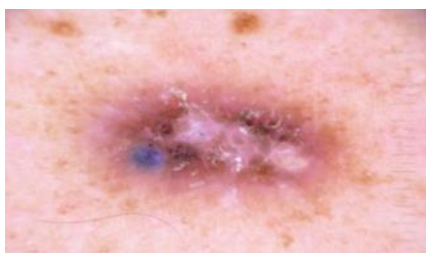


Figure 8. image is predicting the random and preprocessing to get unique images



Figure 9. image is displaying the skin cancer image from the training data

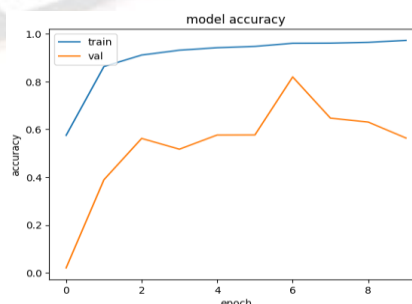


Figure 10. The figure shows the Sensitivity and specificity.

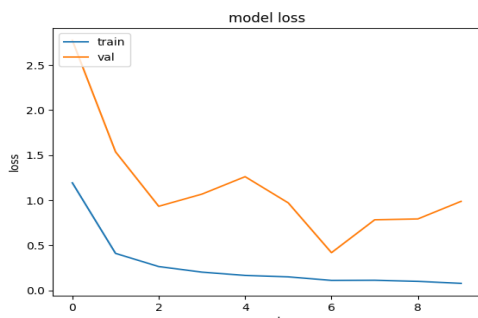


Figure 11. Model Accuracy Graph

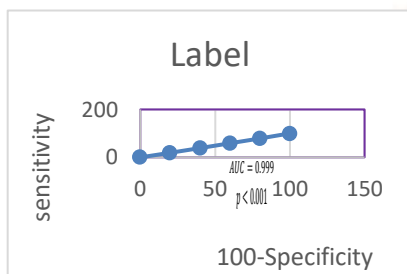


Figure 12. Model Loss Graph

Model evaluation in deep learning is assessing how well a trained neural network model performs on a dataset it has not seen before. This is typically done by measuring the model's accuracy, precision, recall, F1 score, and/or other performance metrics on a validation or test dataset.

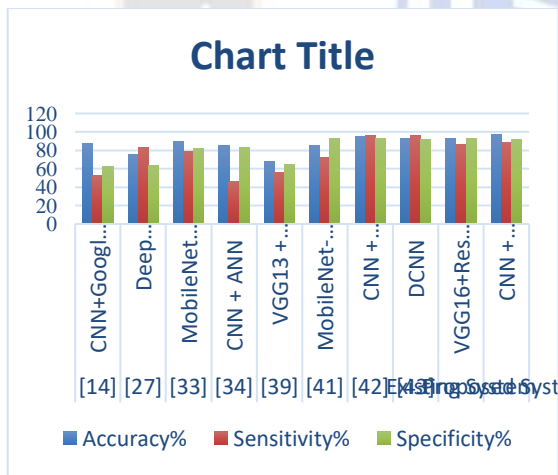


Figure 13. Model Comparison

CONFUSION MATRIX

In deep learning and machine learning, a confusion matrix is a common technique for assessing how well a classification model is performing. The number of true positives, true negatives, false positives, and false negatives that the model correctly predicted are displayed in this table. The real labels for the data are displayed, debunking these presumptions. The actual labels are shown in the rows of a confusion matrix, while the anticipated labels are shown in the columns. True positives (TP) and true negatives (TN) are terms used to describe whether a model correctly predicts the outcome of a

positive sample. False positives and false negatives are terms used to describe samples with incorrectly expected results in either a positive or negative direction. Accuracy, precision, recall, and F1-score are a few performance metrics that may be computed using the confusion matrix. While precision is determined by dividing the total number of true positives by the total number of positive predictions (TP+FP), accuracy is determined by dividing the total number of right predictions (TP+TN) by the total number of samples.

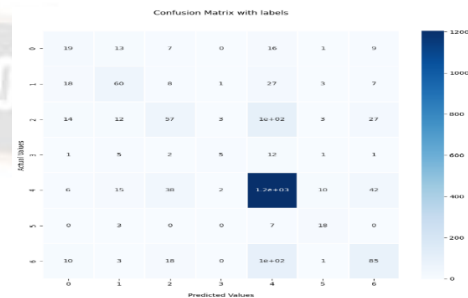


Figure 14: ResNet_50 Confusion Matrix

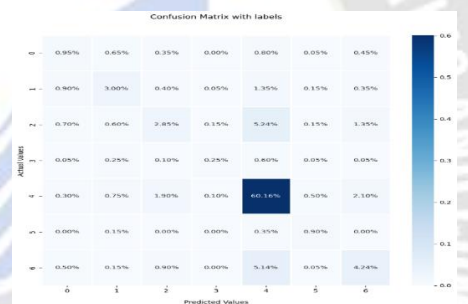


Figure 15: ResNet_50 confusion matrix with labels

VI. CONCLUSION AND FUTURE SCOPE

Using solely digital image processing, this study created an automated method to categories dermatofibroma, nevus pigmentosa, squamous cell carcinoma, and malignancy. Three hidden layers, a fully linked layer, SoftMax activation, three hidden layers with three different filter sizes, and successively sixteen, 32, and 64 channel outputs are all components of the CNN model employed in this study. SGD, RMSprop, Adam, and Naadam optimizers are used to complete the optimization in the suggested model. According to the findings of completed testing, the CNN version with Adam optimizer performs excellently in categorizing the dataset of benign tumor lesions and skin cancer lesions with 99% accuracy, missing zero. 0346, and precision costs roughly \$1, bear that in mind. Based on performance data, the gadget concludes that the suggested version is promising for use as a cutting-edge tool for healthcare professionals to choose the inspection of benign tumors or skin cancer. Similar research can create classifications for the many different kinds of skin cancer, including the most severe ones, as well as for different skin illnesses. Research on skin cancer detection is mostly focused on determining if a particular lesion image is malignant or not.

The question of whether a certain skin cancer symptom manifests on any region of a patient's body can't be answered by the most recent research, though. The study has thus far concentrated on the minor issue of the category of the sign picture. To try to uncover the solution to the question that frequently occurs, destiny studies may include whole-body photographs. Independent whole-frame photos will streamline and automate the photo acquisition process. In the area of in-depth learning, the concept of automobile organization has recently evolved. Auto-agency is a method of unsupervised learning that aspires to recognize family members or fashions among the dataset's photo samples. Expert systems can now get a higher level of feature representation thanks to convolutional neural network-based methods for the automotive industry [47]. Now being studied and enhanced is the version called "Car-company." However, its observation can help image processing systems become more accurate. When the time comes, especially in the realm of medical imaging, where the most accurate statistics of capabilities are crucial for the correct disease prognosis.

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